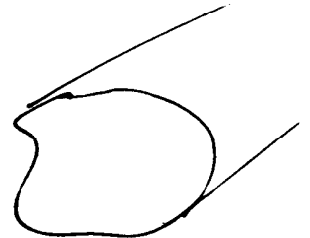
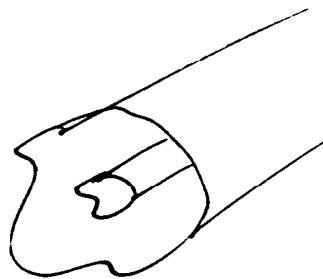
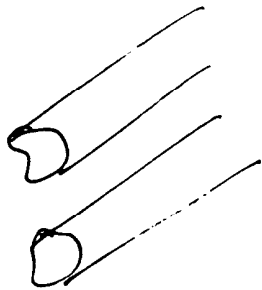


PROPAGAZIONE GUIDATA

ESISTE STRUTTURA CHE SUPPORTA
LA PROPAGAZIONE

SUPERFICIE CILINDRICHE INDEFINITE
DI MATERIALE CONDUTTORE ELETTRICO
PERFETTO

DIELETTRICO OMOGENEO, ISOTROPO, PRIVO DI
PERDITE



CILINDRI

RETTI

RICERCA DELLE SOLUZIONI LIBERE

$$\nabla \times \underline{E} = -j\omega\mu \underline{H} \quad \nabla \cdot \underline{\epsilon E} = 0$$

$$\nabla \times \underline{H} = j\omega\epsilon \underline{E} \quad \nabla \cdot \underline{\mu H} = 0$$

BASTA CONSIDERARE LE

SFRUTTIAMO LA GEOMETRIA, E PONIAMO:

$$\underline{E} = \underline{E}_t + E_z \underline{i}_z \quad \underline{E}_t = E_x \underline{i}_x + E_y \underline{i}_y$$

$$\underline{H} = \underline{H}_t + H_z \underline{i}_z \quad \underline{H}_t = H_x \underline{i}_x + H_y \underline{i}_y$$

Proiettiamo sul piano trasverso:

$$\underline{i}_z \times \nabla \times \underline{E}_t + \nabla \times E_z \underline{i}_z = -j\omega\mu \underline{H}_t - j\omega\mu H_z \underline{i}_z \quad \underline{i}_z \times \underline{i}_z = 0$$

$$\underline{i}_z \times \nabla \times \underline{H}_t + \nabla \times H_z \underline{i}_z = j\omega\epsilon \underline{E}_t + j\omega\epsilon E_z \underline{i}_z \quad \underline{i}_z \times \underline{i}_z = 0$$

Ricordando:

$$\underline{A} \times (\underline{B} \times \underline{C}) = \underline{B} (\underline{A} \cdot \underline{C}) - \underline{C} (\underline{A} \cdot \underline{B})$$

$$\underline{i}_z \times \nabla \times \underline{E}_t = \nabla (\underbrace{\underline{i}_z \cdot \underline{E}_t}_0) - \underline{E}_t (\underline{i}_z \cdot \nabla)$$

$$\underline{i}_z \cdot \nabla = \underline{i}_z \cdot \left(\underline{i}_x \frac{\partial}{\partial x} + \underline{i}_y \frac{\partial}{\partial y} + \underline{i}_z \frac{\partial}{\partial z} \right)$$

$$= \frac{\partial}{\partial z}$$

$$\underline{i}_z \times \nabla \times \underline{E}_z \underline{i}_z = \underline{i}_z \times \begin{vmatrix} \underline{i}_x & \underline{i}_y & \underline{i}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & E_z \end{vmatrix} =$$

$$= \underline{i}_z \times \left(\underline{i}_x \frac{\partial E_z}{\partial y} - \underline{i}_y \frac{\partial E_z}{\partial x} \right) = \underline{i}_y \frac{\partial E_z}{\partial y} + \underline{i}_x \frac{\partial E_z}{\partial x}$$

PERTANTO =

$$-\frac{\partial}{\partial z} \underline{E}_t + \nabla_t \underline{E}_z = -j\omega\mu \underline{i}_z \times \underline{H}_t$$

$$-\frac{\partial}{\partial z} \underline{H}_t + \nabla_t \underline{H}_z = j\omega\varepsilon \underline{i}_z \times \underline{E}_t$$

PROIETTIAMO ~~IL VETTORE~~ LONGITUDINALMENTE:

$$\underline{i}_z \cdot \nabla \times \underline{E}_t + \nabla \times \underline{E}_z \underline{i}_z = -j\omega\mu \underline{H}_t - j\omega\mu \underline{H}_z \underline{i}_z$$

$$\underline{i}_z \cdot \nabla \times \underline{H}_t + \nabla \times \underline{H}_z \underline{i}_z = j\omega\varepsilon \underline{E}_t + j\omega\varepsilon \underline{E}_z \underline{i}_z$$

$$\underline{i}_z \cdot \nabla \times \underline{E}_t = -j\omega\mu \underline{H}_z \underline{i}_z \rightarrow \underline{H}_z = -\frac{1}{j\omega\mu} \nabla_t \cdot \underline{E}_t \times \underline{i}_z$$

$$\begin{cases} \underline{H}_z = \frac{1}{j\omega\mu} \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) \\ \underline{E}_z = \frac{1}{j\omega\varepsilon} \nabla_t \cdot (\underline{H}_t \times \underline{i}_z) \end{cases}$$

E QUINDI:

$$\begin{cases} -\frac{\partial}{\partial z} \underline{E}_t = j\omega\mu \left[(\underline{H}_t \times \underline{i}_z) + \frac{1}{k^2} \nabla_t \nabla_t \cdot (\underline{H}_t \times \underline{i}_z) \right] \\ -\frac{\partial}{\partial z} \underline{H}_t = j\omega\varepsilon \left[(\underline{i}_z \times \underline{E}_t) + \frac{1}{k^2} \nabla_t \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) \right] \end{cases}$$

$$\underline{E}_z =$$

$$\underline{H}_z =$$

Poniamo:

$$\underline{E}_t = \underline{e}(\underline{t}) V(z) \quad \underline{t} = x \underline{i}_x + y \underline{i}_y$$

$$\underline{H}_t = \underline{h}(\underline{t}) \underline{I}(z)$$

$\underline{e}(\underline{t}), \underline{h}(\underline{t}) \rightarrow$ funzioni vettoriali di modo

$V(z), \underline{I}(z) \rightarrow$ " scalari di modo

Studiamo alcune configurazioni:

(TEM)

$$E_z = H_z = 0$$

$$\underline{E} = \underline{E}_t \quad \underline{H} = \underline{H}_t$$

(TE)

$$E_z = 0$$

$$\underline{E} = \underline{E}_t \quad \underline{H} = \underline{H}_t + H_z \underline{i}_z$$

(TM)

$$H_z = 0$$

$$\underline{E} = \underline{E}_t + E_z \underline{i}_z \quad \underline{H} = \underline{H}_t$$

DEFINISCONO QUALSIASI CONFIGURAZIONE
(SI VEDRA')

TEM

$$E_z = H_z = 0$$

$$\underline{E} = \underline{E}_t$$

$$\underline{H} = \underline{H}_t$$

$$\begin{cases} -\frac{\partial}{\partial z} \underline{E}_t = j\omega\mu (\underline{H}_t \times \underline{i}_z) & \rightarrow -\underline{e} \frac{dV}{dz} = j\omega\mu I (\underline{h} \times \underline{i}_z) \\ -\frac{\partial}{\partial z} \underline{H}_t = j\omega\varepsilon (\underline{i}_z \times \underline{E}_t) & \rightarrow -\underline{h} \frac{dI}{dz} = j\omega\varepsilon V (\underline{i}_z \times \underline{e}) \end{cases}$$

$$\underline{e} = \frac{j\omega\mu I}{-\frac{dV}{dz}} (\underline{h} \times \underline{i}_z) \rightarrow \underline{e} = a (\underline{h} \times \underline{i}_z)$$

$$\underline{i}_z \times \underline{e} = a \underline{i}_z \times (\underline{h} \times \underline{i}_z) = a \underline{h}$$

$$\underline{e} = a (\underline{h} \times \underline{i}_z) \quad \underline{h} = \frac{1}{a} (\underline{i}_z \times \underline{e})$$

$$\underline{h} = \frac{j\omega\varepsilon V}{-\frac{dI}{dz}} (\underline{i}_z \times \underline{e})$$

$$\frac{j\omega\mu I}{-\frac{dV}{dz}} = a \quad \rightarrow \quad -\frac{dV}{dz} = j\omega\mu \frac{1}{a} I$$

$$\frac{j\omega\varepsilon V}{-\frac{dI}{dz}} = \frac{1}{a} \quad \rightarrow \quad -\frac{dI}{dz} = j\omega\varepsilon a V$$

de cui si ricava V, I

ed $\underline{e}, \underline{h}$?

$$E_z = 0 \quad \nabla_t \cdot (\underline{H}_t \times \underline{i}_z) = 0 \quad \rightarrow \quad \nabla_t \times \underline{H}_t = 0$$

$$H_z = 0 \quad \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) = 0 \quad \rightarrow \quad \nabla_t \times \underline{E}_t = 0$$

Ricordando: $\nabla \cdot (\underline{a} \times \underline{b}) = \underline{b} \cdot \nabla \times \underline{a} - \underline{a} \cdot \nabla \times \underline{b}$

$$I(z) \nabla_t \times \underline{h} = 0$$

$$\nabla_t \times \underline{h} = 0$$

$$\underline{h} = -\nabla_t \psi$$

$$V(z) \nabla_t \times \underline{e} = 0$$

$$\nabla_t \times \underline{e} = 0$$

$$\underline{e} = -\nabla_t \phi$$

Sempre da:

$$\begin{cases} \nabla_t \cdot (\underline{H}_t \times \underline{i}_z) = 0 \rightarrow I(z) \nabla_t \cdot (\underline{h} \times \underline{i}_z) = \phi & \nabla_t \cdot \underline{e} = \phi \\ \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) = \phi \rightarrow V(z) \nabla_t \cdot (\underline{i}_z \times \underline{e}) = 0 & \nabla_t \cdot \underline{h} = \phi \end{cases}$$

$$\nabla_t \cdot \underline{e} = -\nabla_t \cdot \nabla_t \phi = -\nabla_t^2 \phi = 0$$

$$\nabla_t \cdot \underline{h} = -\nabla_t \cdot \nabla_t \psi = -\nabla_t^2 \psi = 0$$

$$\boxed{\nabla_t^2 \phi = 0 \quad \nabla_t^2 \psi = 0}$$

$\phi, \psi \rightarrow$ funzioni armoniche

$$\underline{e} = -\nabla_t \phi$$

$$\underline{h} = \frac{1}{a} (\underline{i}_z \times \underline{e})$$

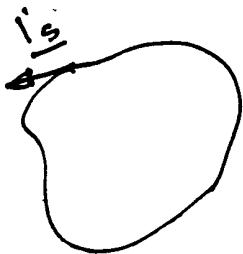
$$\underline{h} = -\nabla_t \psi$$

$$\underline{e} = (\underline{h} \times \underline{i}_z) a$$

$$\nabla^2 \phi = 0 \quad \text{con } \phi \Big|_{\text{contorno}} = ?$$

$$\underline{E} \cdot \underline{i}_s \Big|_C = \emptyset = \underline{E}_t \cdot \underline{i}_s \Big|_C = V \underline{e} \cdot \underline{i}_s \Big|_C = \emptyset$$

$$\nabla_t \phi \cdot \underline{i}_s \Big|_C = \emptyset = \frac{\partial \phi}{\partial s} \Big|_C = \emptyset$$



$$\phi \Big|_C = \text{cost}$$

Una funzione armonica costante sul contorno,
 se la sezione è semplicemente connessa,
 mantiene lo stesso valore costante su tutta la
 sezione.

$$\underline{e} = -\nabla \phi = -\nabla \text{cost.} = \emptyset$$

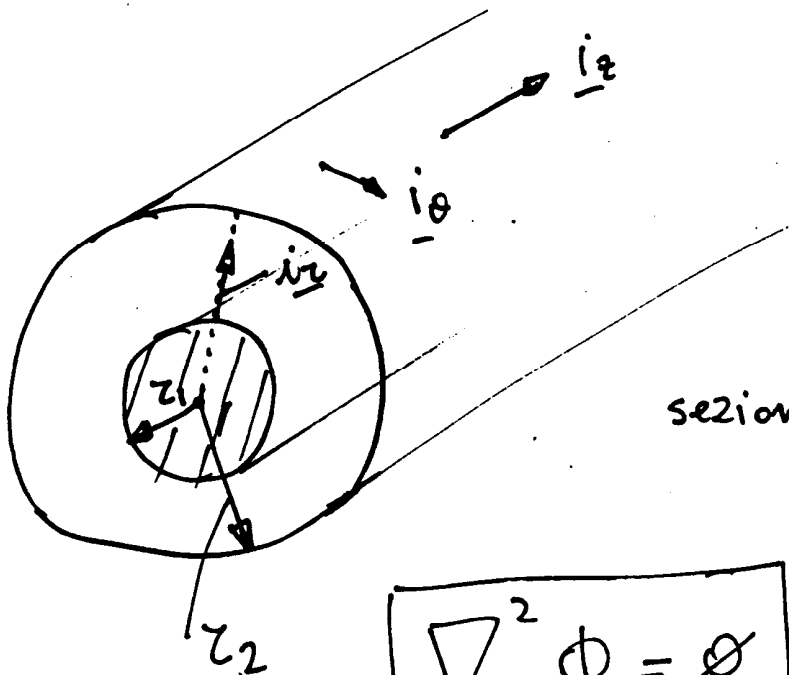
Quindi campi nulli.

Se la sezione è moltiplicemente connessa:

$$\phi \Big|_{C_i} = \text{cost.} \quad \text{e quindi } \underline{e} \neq \emptyset$$

Esistenze di modo TEM

Esempio: TEM in cavo coassiale.



sezione doppiamente
connessa

$$\nabla_t^2 \phi = 0$$

$$\phi = \phi(\underline{t}) = \phi(r, \theta)$$

$$\phi(r_1, \theta) = \phi_1 \text{ (costante)}$$

$$\phi(r_2, \theta) = \phi_2 \text{ (")}$$

$$\phi = \phi(r)$$

$$\nabla_t^2 \phi = \frac{1}{r} \frac{d}{dr} \left(r \frac{d\phi}{dr} \right) = 0$$

$$r_1 \leq r \leq r_2$$



$$\frac{d}{dz} \left(r \frac{d\phi}{dz} \right) = 0 \rightarrow r \frac{d\phi}{dz} = -A$$

$$\downarrow$$

$$d\phi = -\frac{A}{r} dz$$

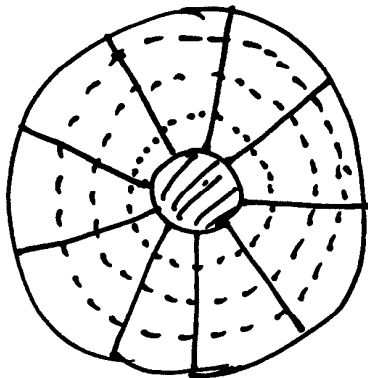
$$\phi(r) = -A \lg r + C$$

$$\underline{e} = -\nabla\phi = -\frac{\partial\phi}{\partial r} \underline{i}_r = \frac{A}{r} \underline{i}_r$$

$$\underline{h} = \frac{1}{a} \underline{i}_z \times \underline{e}$$

$$\underline{E} = \underline{E}_t = \underline{e} V = \frac{A}{r} \underline{i}_r V(z)$$

$$\underline{H} = \underline{H}_t = \underline{h} I = \frac{1}{a} \frac{A}{r} \underline{i}_\theta I(z)$$

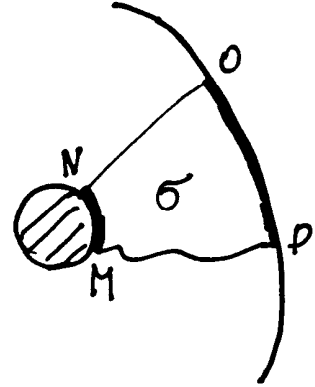


Fissiamo A , e in modo da attribuire a

V, I significato fisico.

$$\nabla \times \underline{E} = -j\omega\mu \underline{H}$$

$$\iint_{\sigma} \nabla \times \underline{E}_t \cdot \underline{i}_z d\sigma = -j\omega\mu \iint_{\sigma} \underline{H}_t \cdot \underline{i}_z d\sigma$$



$$\oint_{MNOP} \underline{E}_t \cdot \underline{i}_s d\sigma = 0$$

$$\int_M^N \dots + \int_N^O \dots + \int_O^P \dots + \int_P^M \dots = 0$$

$$\int_M^O \underline{E}_t \cdot \underline{i}_s d\sigma = \int_M^P \underline{E}_t \cdot \underline{i}_s d\sigma = \text{tensione o differenza di potenziale}$$

$$\int_M^O \underline{E}_t \cdot \underline{i}_s d\sigma = \int_{r_1}^{r_2} \frac{A}{r} V(z) \underline{i}_r \cdot \underline{i}_r dr =$$

$$= A V(z) \log \frac{r_2}{r_1} = V(z) \text{ alle } V(z) \text{ si dà il significato di...}$$

$$\text{da cui } A = \frac{1}{\log \frac{r_2}{r_1}}$$

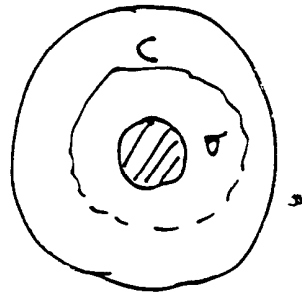
e quindi:

$$\underline{E}_t = \underline{E} = \frac{V(z)}{\pi \rho \frac{z_2}{z_1}} \underline{i}_z$$

DALLA 2^a EQ. DI MAXWELL:

$$\nabla \times \underline{H} = j\omega \varepsilon \underline{E} + \underline{J}$$

$$\iint_{\sigma} \nabla \times \underline{H}_t \cdot \underline{i}_z \, d\sigma = j\omega \varepsilon \iint_{\sigma} \underline{E}_t \cdot \underline{i}_z \, d\sigma + \iint_{\sigma} \underline{J} \cdot \underline{i}_z \, d\sigma$$



$$\oint_C \underline{H}_t \cdot \underline{i}_c \, dc = I_c(z)$$

dove $I_c(z)$ è la corrente nel conduttore compresa con il campo \underline{H}_t ; fuori del conduttore la corrente è nulla

Se C è una circonferenza di raggio z generico

Si ha:

$$\int_0^{2\pi} \left(\frac{1}{a} \frac{A}{\pi} \underline{I}(z) \underline{i}_\theta \right) \cdot \left(\underline{i}_\theta \pi d\theta \right) = \underline{I}_c(z)$$

funzione scalare
di modo

corrente media
conduttore I_c

Se poniamo che siano uguali: $I_c = I(z)$

$$\frac{1}{a} \frac{A}{\pi} \underline{I}(z) \pi 2\pi = \underline{I}(z)$$

$$a = 2\pi A = \frac{2\pi}{\lg \frac{z_2}{z_1}}$$

e quindi

$$\underline{H}_t = \underline{H} = \frac{1}{2\pi z} \underline{I}(z) \underline{i}_\theta$$

$V \rightarrow$ dimensioni di una tensione [Volt]
 $I \rightarrow$ " " " corrente [A]

$$\underline{e} \equiv [L^{-1}] ; \quad \underline{h} \equiv [L^{-1}]$$

Si è trovato: a , A

$$\begin{cases} -\frac{dV}{dz} = j\omega\mu \frac{1}{a} I \\ -\frac{dI}{dz} = j\omega\varepsilon a V \end{cases}$$

Nella teoria delle linee, si era trovato:

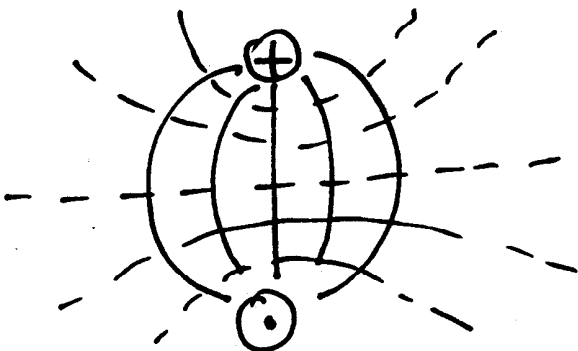
$$\begin{cases} -\frac{dV}{dz} = j\omega L I \\ -\frac{dI}{dz} = j\omega C V \end{cases}$$

Cavo coassiale \equiv linee di trasmissione

$$C = \frac{2\pi\varepsilon}{\log \frac{r_2}{r_1}}$$

$$L = \frac{\mu}{2\pi} \log \frac{r_2}{r_1}$$

C, L per unità di lunghezza -



Modi TE

$$E_z = 0$$

G-16

$$\underline{E} = \underline{E}_t = \underline{e}(z) V(z)$$

$$\underline{H} = \underline{H}_t + H_z \underline{i}_z = \underline{h} I(z) + H_z \underline{i}_z$$

Eq. trasv.

$$\begin{cases} -\frac{\partial \underline{E}_t}{\partial z} = j\omega\mu \left[(\underline{H}_t \times \underline{i}_z) + \frac{1}{k^2} \nabla_t \nabla_t \cdot (\underline{H}_t \times \underline{i}_z) \right] \\ -\frac{\partial \underline{H}_t}{\partial z} = j\omega\varepsilon \left[(\underline{i}_z \times \underline{E}_t) + \frac{1}{k^2} \nabla_t \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) \right] \end{cases}$$

$$\begin{cases} E_z = \frac{1}{j\omega\varepsilon} \nabla_t \cdot (\underline{H}_t \times \underline{i}_z) \rightarrow \boxed{\nabla_t \cdot (\underline{H}_t \times \underline{i}_z) = 0} \\ H_z = \frac{1}{j\omega\mu} \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) \end{cases}$$

e quindi:

$$\begin{cases} -\underline{e} \frac{dV}{dz} = j\omega\mu I (\underline{h} \times \underline{i}_z) \\ -\underline{h} \frac{dI}{dz} = j\omega\varepsilon V \left[(\underline{i}_z \times \underline{e}) + \frac{1}{k^2} \nabla_t \nabla_t \cdot (\underline{i}_z \times \underline{e}) \right] \end{cases}$$

$$\underline{e} = \frac{j\omega\mu I}{-\frac{dV}{dz}} (\underline{h} \times \underline{i}_z) = a$$

$$\begin{cases} -\frac{dV}{dz} = \frac{1}{a} j\omega\mu I \\ \underline{e} = a (\underline{h} \times \underline{i}_z) \end{cases}$$

- arbitratezza nella scelta di a
- impossibilità di associare significato fisico a V ed I
- poniamo $a=1$

quindi: $\underline{e} = (\underline{h} \times \underline{i}_z)$ $\underline{i}_z \times \underline{e} = \underline{i}_z \times \underline{h} \times \underline{i}_z = \underline{h}$

pertanto:

$$-\underline{h} \frac{dI}{dz} = j\omega \epsilon V \underline{h} = j \frac{\omega \epsilon V}{k^2} \nabla_t \cdot \nabla_t \cdot \underline{h}$$

↓

$$\nabla_t \cdot \nabla_t \cdot \underline{h} = \frac{k^2}{j\omega \epsilon V} \left(-\frac{dI}{dz} - j\omega \epsilon V \right) \underline{h}$$

↓

$$\nabla_t \cdot \nabla_t \cdot \underline{h} = - \underbrace{\left(k^2 \left(\frac{dI/dz}{j\omega \epsilon V} + 1 \right) \right)}_{\cos t} \underline{h}$$

$$\left\{ \begin{array}{l} k^2 \left(\frac{dI/dz}{j\omega \epsilon V} + 1 \right) = \cos t = k_{tH}^2 \\ \nabla_t \cdot \nabla_t \cdot \underline{h} + k_{tH}^2 \underline{h} = 0 \end{array} \right.$$

$$\frac{\omega^2 \epsilon \mu}{j\omega \epsilon V} \frac{dI}{dz} + k^2 = k_{tH}^2$$

$$\begin{array}{l}
 -\frac{dI}{dz} = j \frac{k^2 - k_{tH}^2}{\omega\mu} V \\
 \nabla_t \nabla_t \cdot \underline{h} + k_{tH}^2 \underline{h} = 0 \\
 -\frac{dV}{dz} = j\omega\mu I \\
 \underline{e} = \underline{h} \times \underline{i}_z
 \end{array}$$

poniamo

$$k_{zH}^2 = k^2 - k_{tH}^2$$

e valutiamo:

$$\frac{k_{zH}}{\omega\mu} \equiv \left[\frac{\omega\sqrt{\epsilon\mu}}{\omega\mu} \right] \equiv \left[\sqrt{\frac{\epsilon}{\mu}} \right] \equiv \left[\frac{1}{Z} \right]$$

e quindi:

$$\frac{k_{zH}}{\omega\mu} = \frac{1}{Z_{0H}} \rightarrow \omega\mu = k_{zH} Z_{0H}$$

$$\begin{cases}
 -\frac{dI}{dz} = j \frac{k_{zH}}{Z_{0H}} V \\
 -\frac{dV}{dz} = j k_{zH} Z_{0H} I
 \end{cases}
 \rightarrow \text{modo } k_{zH} \rightarrow \underline{V}, I$$

In ogni caso è: $k_z = \omega\sqrt{\epsilon\mu} \sqrt{\frac{\mu}{\epsilon}} = \omega\mu$

e quindi anche in il modo TEM, è possibile usare le stesse notazioni.

Risolviamo:

$$\nabla_t \nabla_t \cdot \underline{h} + k_{tH}^2 \underline{h} = 0$$

da $\epsilon_z = 0$
 \downarrow

$$\nabla_t \cdot (\underline{H}_t \times \underline{i}_z) = 0$$

$$\nabla_t \times \underline{h} = 0$$

$$\underline{h} = -\nabla_t \psi$$

e quindi:

$$-\nabla_t \nabla_t \cdot \nabla_t \psi - k_{tH}^2 \nabla_t \psi = 0$$

$$\nabla_t (\nabla_t \cdot \nabla_t \psi + k_{tH}^2 \psi) = 0$$

$$\nabla_t^2 \psi + k_{tH}^2 \psi = \text{cost}$$

$$\psi_1 = \frac{\text{cost}}{k_{tH}^2}$$

$$\psi = \psi_0 + \psi_1$$

\downarrow
omogenea
corrispondente

$$\underline{h} = -\nabla_t \psi = -\nabla_t \psi_0 - \nabla_t \psi_1 = -\nabla_t \psi_0$$

Soluzioni:

$$\nabla_t^2 \psi + k_{tH}^2 \psi = 0$$

con le condizioni al contorno:

$$\underline{E} \cdot \underline{i}_c \Big|_c = \emptyset = \underline{E}_t \times \underline{i}_m \Big|_c = \emptyset = V \underline{e} \times \underline{i}_m \Big|_c = \underline{e} \times \underline{i}_m \Big|_c = \emptyset$$

$$\underline{i}_m \times \underline{h} \times \underline{i}_z \Big|_c = \underline{h} (\underline{i}_m \cdot \underline{i}_z) - \underline{i}_z (\underline{i}_m \cdot \underline{h}) \Big|_c = \emptyset$$

$$\underline{i}_m \cdot \underline{h} \Big|_c = \emptyset = \underline{i}_m \cdot \nabla_t \psi \Big|_c = \frac{\partial \psi}{\partial m} \Big|_c = \emptyset \text{ (Neuman)}$$

Quindi per i modi TE:

$$\nabla_t^2 \psi + k_{tH}^2 \psi = 0$$

$$\frac{\partial \psi}{\partial m} \Big|_c = 0$$

si determinano ψ e k_{tH} e quindi

V, I .

NESSUNA LIMITAZIONE SUL TIPO
DI CONTORNO

Modi TM

$$H_z = 0$$

$$\underline{E} = \underline{E}_t + E_z \underline{i}_z = \underline{e} V(z) + E_z \underline{i}_z$$

$$\underline{H} = \underline{H}_t = \underline{h} I(z)$$

Operando come prima:

$$\begin{cases} -\frac{dV}{dz} = j \frac{k^2 - k_{tE}^2}{\omega \epsilon} I = j k_{zE} Z_{0E} I \\ -\frac{dI}{dz} = j \omega \epsilon V = j \frac{k_{zE}}{Z_{0E}} V \end{cases}$$

$$\underline{h} = \underline{i}_z \times \underline{e}$$

$$\nabla_t \nabla_t \cdot \underline{e} + k_{tE}^2 \underline{e} = 0$$

$$\nabla_t^2 \phi + k_{tE}^2 \phi = 0$$

$$\underline{e} = -\nabla_t \phi$$

$$\phi \Big|_c = 0 \quad (\text{Dirichlet})$$

Infatti:

$$\underline{E} \times \underline{i}_m \Big|_c = 0 \rightarrow \left(\underline{E}_t + E_z \underline{i}_z \right) \times \underline{i}_m \Big|_c = 0$$

E_z è tutta tangente

$$\nabla_t \cdot \left(\underline{H}_t \times \underline{i}_z \right) \Big|_c = 0 \quad \text{I} \quad \nabla_t \cdot \left(\underline{h} \times \underline{i}_z \right) \Big|_c = 0$$

$$\nabla_t \cdot \left(\underline{h} \times \underline{i}_z \right) \Big|_c = \nabla_t \cdot \underline{e} \Big|_c = - \nabla^2 \phi \Big|_c = 0 \rightarrow k_{tE}^2 \phi \Big|_c = 0$$

$$\boxed{\phi_c = 0}$$

$$\underline{i}_m \times \underline{E}_t \Big|_c = 0 \quad V(z) \underline{i}_m \times \underline{e} \Big|_c = \underline{i}_m \times \underline{e} \Big|_c =$$

$$= \underline{i}_s \cdot \underline{e} \Big|_c = - \underline{i}_s \cdot \nabla \phi \Big|_c = - \frac{\partial \phi}{\partial s} \Big|_c = 0$$

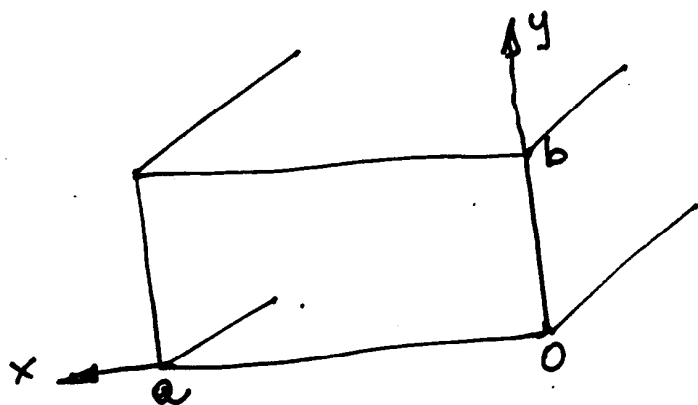
così $\boxed{\phi_c = \text{cost}}$

ϕ sul contorno deve essere cost e nulla,

quindi

$$\boxed{\phi_c = 0}$$

Esempio: Guide d'onda rettangolare. 6-23



$$b = \frac{1}{2} a \text{ (standard)}$$

Modi TE

Equaz. trovate

$$\begin{cases} -\frac{dV}{dz} = j k_{zH} Z_{0H} I \\ -\frac{dI}{dz} = j \frac{k_{zH}}{Z_{0H}} V \end{cases}$$

$$\nabla_t^2 \psi + k_{tH}^2 \psi = 0$$

$$\left. \frac{\partial \psi}{\partial n} \right|_c = 0$$

$$\psi = \psi(\underline{t}) = \psi(x \underline{i}_x + y \underline{i}_y) = \psi(x, y)$$

Soluzioni del tipo: $\psi(x, y) = \psi_x(x) \psi_y(y)$

$$\frac{\partial^2 \psi_x}{\partial x^2} \psi_y + \frac{\partial^2 \psi_y}{\partial y^2} \psi_x + k_{tH}^2 \psi_x \psi_y = 0$$

Dividendo per $\psi_x \psi_y$ certamente $\neq 0$

$$\underbrace{\frac{1}{\psi_x} \frac{\partial^2 \psi_x}{\partial x^2}}_{\text{cost}} + \underbrace{\frac{1}{\psi_y} \frac{\partial^2 \psi_y}{\partial y^2}}_{\text{cost}} + k_{tH}^2 = 0$$

$$\begin{cases} \frac{1}{\psi_x} \frac{\partial^2 \psi_x}{\partial x^2} = -k_x^2 \\ \frac{1}{\psi_y} \frac{\partial^2 \psi_y}{\partial y^2} = -k_y^2 \end{cases} \rightarrow \begin{cases} \frac{\partial^2 \psi_x}{\partial x^2} + k_x^2 \psi_x = 0 \\ \frac{\partial^2 \psi_y}{\partial y^2} + k_y^2 \psi_y = 0 \end{cases}$$

$$\boxed{k_x^2 + k_y^2 = k_{EH}^2}$$

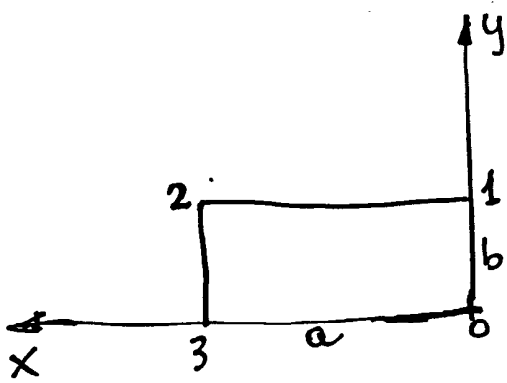
$$\begin{cases} \psi_x(x) = A_x \cos k_x x + B_x \operatorname{sen} k_x x \\ \psi_y(y) = A_y \cos k_y y + B_y \operatorname{sen} k_y y \end{cases} \quad \left. \frac{\partial \psi}{\partial m} \right|_c = 0$$

$$\left. \frac{\partial \psi}{\partial m} \right|_c = \frac{\partial}{\partial m} (\psi_x(x) \psi_y(y)) \Big|_c = 0$$

$$\frac{\partial \psi}{\partial x} = \psi_y \frac{\partial \psi_x}{\partial x} \quad ; \quad \frac{\partial \psi}{\partial y} = \psi_x \frac{\partial \psi_y}{\partial y}$$

$$\frac{\partial \psi_x}{\partial x} = -A_x k_x \operatorname{sen} k_x x + B_x k_x \cos k_x x$$

$$\frac{\partial \psi_y}{\partial y} = -A_y k_y \operatorname{sen} k_y y + B_y k_y \cos k_y y$$



$$0-1) [x=0, 0 \leq y \leq b]$$

$$\left. \frac{\partial}{\partial n} \psi_x \psi_y \right|_{x=0} = \psi_y \left. \frac{\partial \psi_x}{\partial x} \right|_{x=0}$$

$$B_x k_x \psi_y = 0 \text{ for all } k_x \rightarrow \boxed{B_x = 0}$$

$$2-3) [x=a; 0 \leq y \leq b] \quad \psi_y \left. \frac{\partial \psi_x}{\partial x} \right|_{x=a}$$

$$A_x k_x \sin(k_x a) \psi_y = 0 \text{ for all } k_x$$

$$k_x a = m\pi$$

$$\boxed{k_{x,m} = \frac{m\pi}{a}}$$

$$(m=0, 1, 2, \dots)$$

$$0-3) [0 \leq x \leq a, y=0]$$

$$\left. \frac{\partial}{\partial n} \psi_x \psi_y \right|_{y=0} = \psi_x \left. \frac{\partial \psi_y}{\partial y} \right|_{y=0}$$

$$\boxed{B_y = 0}$$

$$1-2) [0 \leq x \leq a, y=b]$$

$$A_y k_y \sin(k_y b) \psi_x = 0$$

$$k_{y,m} = \frac{m\pi}{b} \quad (m=0, 1, 2, \dots)$$

Quindi, posto: $A_x A_y = A$

$$\psi_{m,n}(x,y) = \psi_{x,m}(x) \psi_{y,n}(y) =$$

$$\psi_{m,n} = A \cos\left(\frac{m\pi}{a}x\right) \cos\left(\frac{n\pi}{b}y\right)$$

$$k_{m,n}^2 = \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2$$

Esiste una duplice infinite numerabile di soluzioni del tipo a variabili separate -

Ogni soluzione particolare $\psi_{m,n}$ (autofunzione) si associa ad uno dei valori (autovalori) che il parametro $k_{m,n}$ può assumere -

$$k_{zH} \rightarrow k_{zH}^2 = k^2 - k_{tm,n}^2$$

ψ \downarrow V_H, I_H
 h \rightarrow e

Vediamo le possibili configurazioni:

$$\begin{aligned} m &= 0 \\ n &= 0 \end{aligned}$$

$$k_{tH_{0,0}} = 0$$

$$\psi = A \quad \nabla \psi = 0$$

funzioni vettoriali di modo e campi nulli.

modo TE_{1,0}

$$\begin{aligned} m &= 1 \\ n &= 0 \end{aligned}$$

$$k_{tH_{1,0}} = \frac{\pi}{a}$$

$$\psi_{1,0} = A \cos \frac{\pi}{a} x$$

$$\underline{h} = -\nabla_t \psi = -\frac{\partial \psi}{\partial x} \underline{i}_x - \frac{\partial \psi}{\partial y} \underline{i}_y =$$

$$= A \operatorname{sen} \frac{\pi}{a} x \underline{i}_x$$

$$\underline{e} = \underline{h} \times \underline{i}_z = -A \operatorname{sen} \frac{\pi}{a} x \underline{i}_y$$

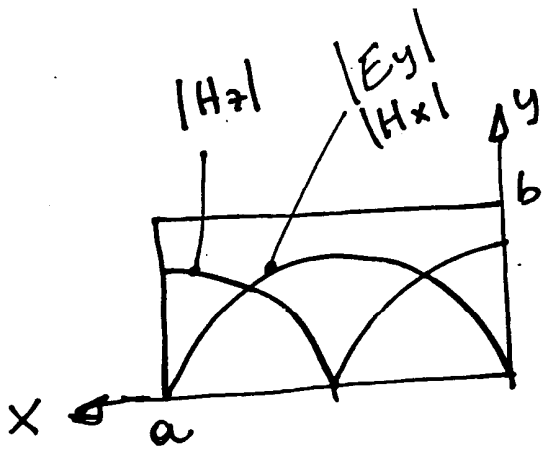
$$\underline{E}_t = -V(z) A \operatorname{sen} \frac{\pi}{a} x \underline{i}_y$$

$$\underline{H}_t = I(z) A \operatorname{sen} \frac{\pi}{a} x \underline{i}_x$$

$$H_z = \frac{1}{j\omega\mu} \nabla_t \cdot (\underline{i}_z \times \underline{E}_t) = -\frac{1}{j\omega\mu} V(z) A \nabla_t \cdot \left(\mu \frac{\pi}{a} \underline{i}_z \times \underline{i}_y \right)$$

$$= \frac{1}{j\omega\mu} V(z) A \nabla_t \cdot \left(\operatorname{sen} \frac{\pi}{a} x \underline{i}_x \right) = \frac{V(z) A \pi}{j\omega\mu a} \omega \frac{\pi}{a} x$$

$$\underline{H}_z = H_z \underline{i}_z$$



Quindi il 1° modo che si trova

$$\text{TE}_{1,0} \quad \text{con } k_{t1,0} = \frac{\pi}{a}$$

$$\text{TE}_{2,0} \quad k_{t2,0} = \frac{2\pi}{a}$$

$$\text{TE}_{0,1} \quad k_{t0,1} = \frac{\pi}{b} > \frac{\pi}{a}$$

Analogamente per modi TM:

$$\Phi_{m,n}(x,y) = B \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{b}y\right)$$

$$\text{con: } k_{tEM,m,n}^2 = \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2$$

Se $m=0$ oppure $n=0 \rightarrow$ campi nulli.

Il primo modo $\neq 0$ è il

$$\underline{\text{TM}_{1,1}} \quad \text{con } k_{tEM,1,1}^2 = \left(\frac{\pi}{a}\right)^2 + \left(\frac{\pi}{b}\right)^2$$

TE si hanno $\infty - 1$

TM si hanno $\infty - 2 \infty$

TEM ? è solo uno - Una autofunzione, un autovettore
 $k_t = 0$

Guida rettangolare - k_z

$$k_z^2 = k^2 - k_{t,m,n}^2$$

Soluzioni espresse come combinazione lineare di funzioni del tipo

$$\exp(\pm j k_z z)$$

→ k_z radice
quadrate di k_z^2
giacente nel 4° quad

- mezzo all'interno della guida senza perdite -

Se $k^2 > k_t^2$... k_z è reale positiva

$k^2 < k_t^2$... k_z è sull'immaginaria negativa

Consideriamo:

$k^2 = k_t^2$ dove k_t deve essere del tipo:

$$k_t^2 = \omega_t^2 \epsilon \mu$$

$$\omega_t = \frac{k_t}{\sqrt{\epsilon \mu}}$$

$$k_t = \frac{2\pi}{\lambda_t}$$

$$k_z = \sqrt{\omega^2 \epsilon \mu - k_t^2}$$

Due casi: 1) $\boxed{\omega > \omega_t}$ ($\lambda < \lambda_t$)

$$k_z^2 = \omega^2 \epsilon \mu - k_t^2$$

$$\frac{k_z^2}{k_t^2} - \frac{\omega^2 \epsilon \mu}{k_t^2} = -1$$

$$\boxed{\frac{\omega^2}{\omega_t^2} - \frac{k_z^2}{k_t^2} = 1}$$

$$\omega \rightarrow \infty$$

$$k_z = \omega \sqrt{\epsilon \mu}$$

- k_z reale positiva
- propagazione senza attenuazione

$k_z = k_z(\omega)$ ramo di iperbole

(iperbole degenera per $k_t = 0$)
(TEM)

2) $\omega < \omega_t$ ($\lambda > \lambda_t$)

$$k_z = \sqrt{\omega^2 \epsilon \mu - k_t^2} = \sqrt{-(k_t^2 - \omega^2 \epsilon \mu)} = j \sqrt{k_t^2 - \omega^2 \epsilon \mu}$$

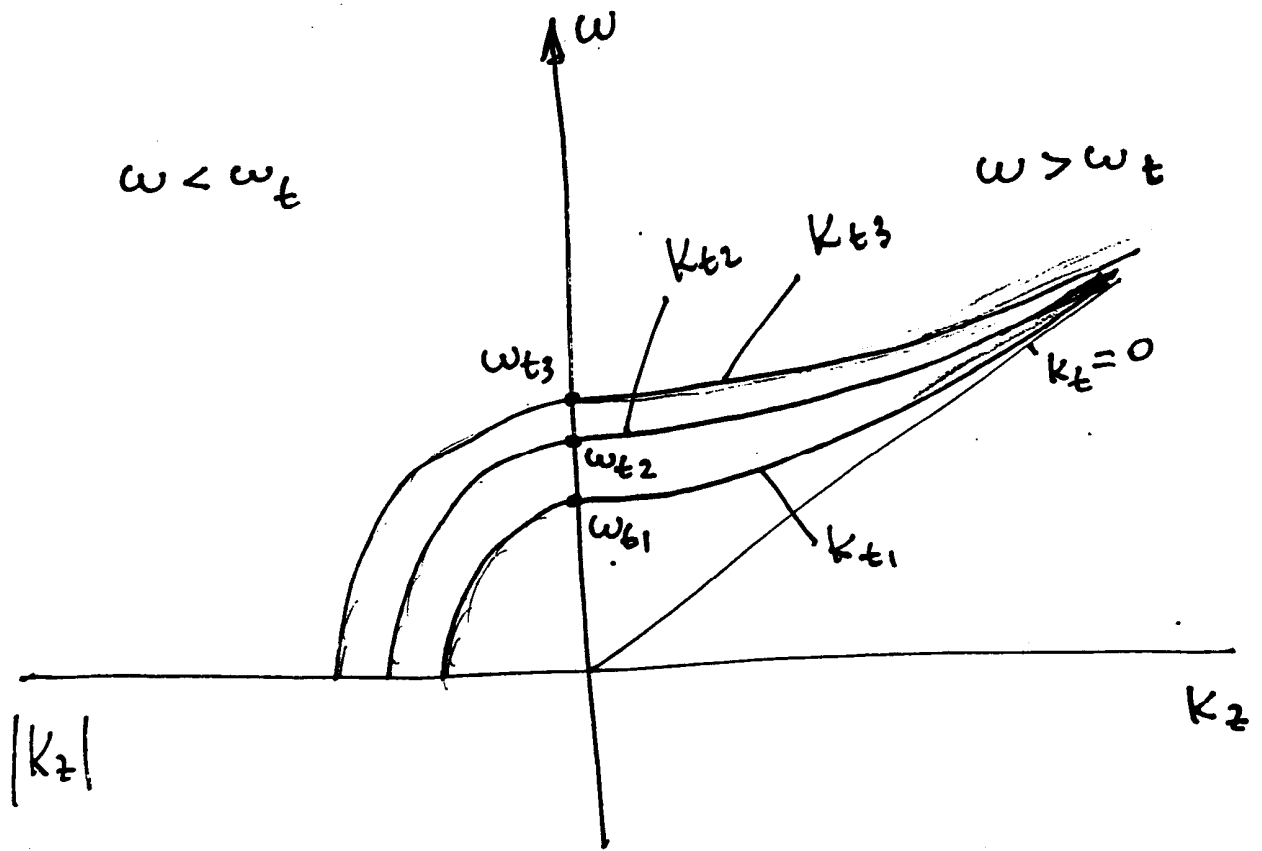
$$|k_z| = \sqrt{k_t^2 - \omega^2 \epsilon \mu} \quad \frac{|k_z|^2}{k_t^2} + \frac{\omega^2 \epsilon \mu}{k_t^2} = 1$$

$$\boxed{\frac{|k_z|^2}{k_t^2} + \frac{\omega^2}{\omega_t^2} = 1}$$

$k_z = k_z(\omega)$ arco di ellisse

- k_z immaginario
- attenuazione

Riprendiamo il diagramma di Brillouin:



$$TE_{1,0} \quad k_{t1,0} = k_{t1} = \frac{\pi}{a} \quad \lambda_{t1,0} = \frac{2\pi}{k_{t1,0}} = 2a$$

dipende solo dalla dimensione a

$$TE_{2,0} \quad k_{t2,0} = \frac{2\pi}{a} \quad \lambda_{t2,0} = \frac{2\pi}{k_{t2,0}} = a$$

$$TE_{0,1} \quad k_{t0,1} = \frac{\pi}{b} \quad \lambda_{t0,1} = \frac{2\pi b}{\pi} = 2b$$

se $b = \frac{a}{2}$

$$\lambda_{t0,1} = a$$

Modi TEModi TM

Impedenza caratteristica

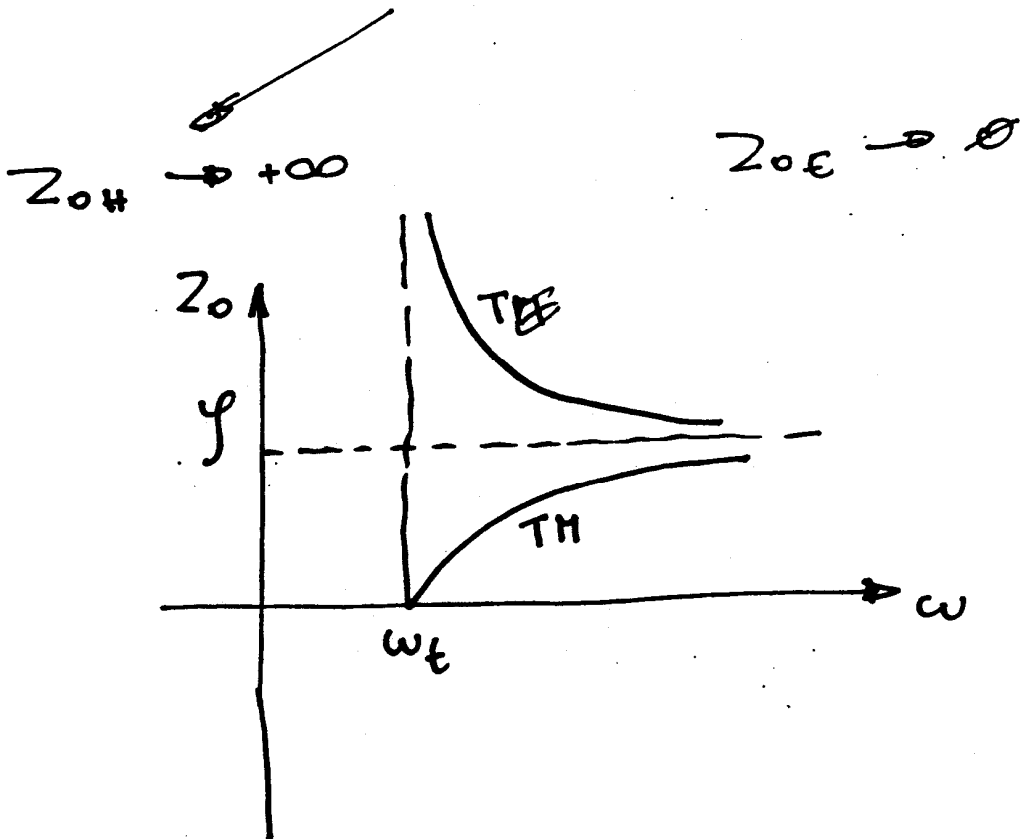
$$Z_{0H} = \frac{\omega \mu}{k_z}$$

$$Z_{0E} = \frac{k_z}{\omega \epsilon}$$

per $\omega > \omega_f$

reale e positiva

per $\omega \rightarrow \infty$ $Z_{0H} = Z_{0E} = \eta = \sqrt{\frac{\mu}{\epsilon}}$

per $\omega \rightarrow \omega_f$ 

$$\lambda_f = \frac{2\pi}{k_z}$$

$$v_f = \frac{\omega}{k_z}$$

$$v_g = \frac{d\omega}{dk_z}$$

per $\omega \rightarrow \omega_t$

∞

∞

0

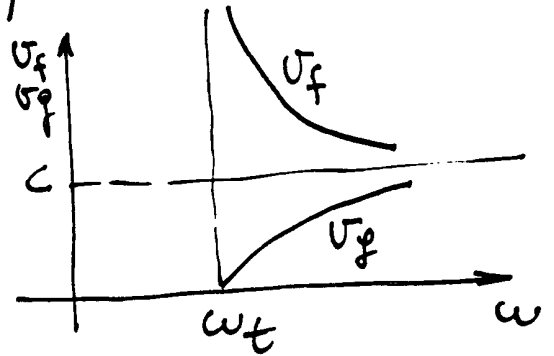
per $\omega \rightarrow \infty$

$$\frac{2\pi}{k}$$

$$\frac{\omega}{k} = c = \frac{1}{\sqrt{\epsilon\mu}}$$

c

$k_z \rightarrow k$



Infetti:

$$v_f = \frac{\omega}{k_z} = \frac{\omega}{\sqrt{\omega^2 \epsilon \mu - k_t^2}}$$

$$v_g = \frac{d\omega}{dk_z} = \frac{1}{\frac{dk_z}{d\omega}} =$$

$$= \frac{1}{\frac{d}{d\omega} \sqrt{\omega^2 \epsilon \mu - k_t^2}} = \frac{1}{\frac{1}{2} (\omega^2 \epsilon \mu - k_t^2)^{-\frac{1}{2}} \cdot 2\omega \epsilon \mu} =$$

$$= \frac{\sqrt{\omega^2 \epsilon \mu - k_t^2}}{\omega \epsilon \mu}$$

$$\boxed{v_f v_g = \frac{1}{\epsilon \mu} = c^2}$$

RAPPRESENTAZIONE DEI CAMPI

TE)

$$E_{zH} = \emptyset$$

$$\nabla_t \cdot (\underline{H}_{tH} \times \underline{i}_z) = 0$$

$$\nabla_t \cdot (\underline{h} \times \underline{i}_z) = \emptyset$$



$$\nabla_t \cdot \underline{e} = \emptyset$$



$$\nabla_t \cdot \underline{E}_{tH} = \emptyset$$

$$\nabla_x \underline{H}_{tH} = \emptyset$$

TM)

$$H_{zE} = \emptyset$$

$$\nabla_t \cdot (\underline{E}_{tE} \times \underline{i}_z) = \emptyset$$

$$\nabla_t \cdot (\underline{e} \times \underline{i}_z) = 0$$

$$\nabla_t \cdot \underline{h} = 0$$

$$\nabla_t \cdot \underline{H}_{tE} = \emptyset$$

$$\nabla_t \times \underline{E}_{tE} = \emptyset$$

$$\underline{E}_t = \underline{E}_{tE} + \underline{E}_{tH} + \underline{E}_{t0} \text{ (TEM)}$$

$$\underline{H}_t = \underline{H}_{tE} + \underline{H}_{tH} + \underline{H}_{t0} \text{ (TEM)}$$